Exploring possible regional variation in the effective control of avian influenza in British poultry

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Introduction

- Both density-dependent and frequency-dependent transmission modes are likely to play a role in between-farm spread of Al. However, the predominant mode operating at farm, regional and industry sector levels is not known.
- The aim of our analysis is to explore potential regional differences in the dependency of models on transmission mode, for avian influenza (AI) in Great Britain (GB).
- Implications relate to model predictions of current Al control measure effectiveness, such as 3km Protection Zones (PZ) and 10km Surveillance Zones (SZ), which may depend upon the transmission mode, i.e., density-independency is suggested to result in ineffective control zones (Truscott et al., 2007).
- Although the declaration of control zones is consistent across GB in the event of an outbreak of highly pathogenic AI, irrespective of region and in line with European Commission directive 2005/94/EC, regional differences in model dependency may suggest a more targeted control strategy is warranted.

Results

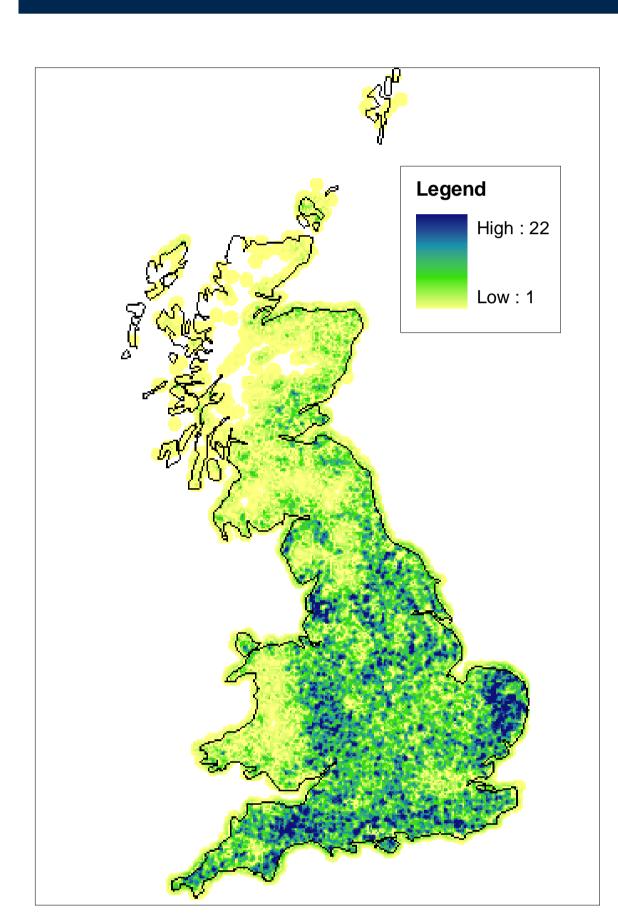


Figure 1. Poultry farm count within **3km** zones for each farm (range: 1 - 22).

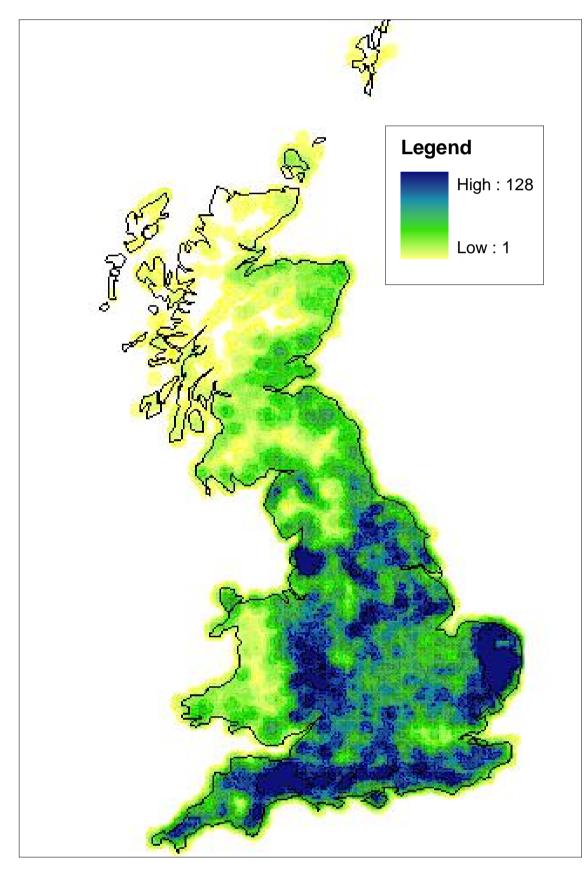


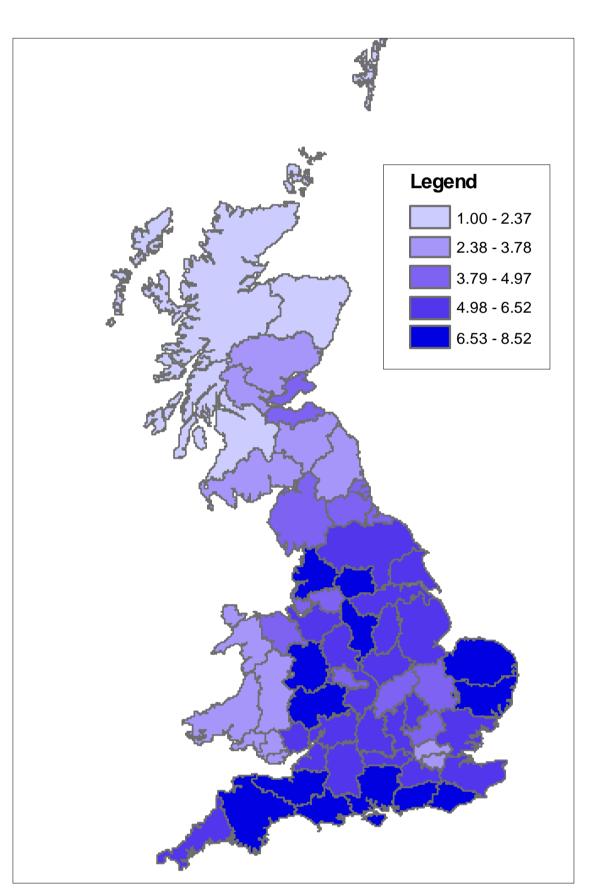
Figure 2. Poultry farm count within **10km** zones for each farm (range: 1 - 128 farms).

Methods

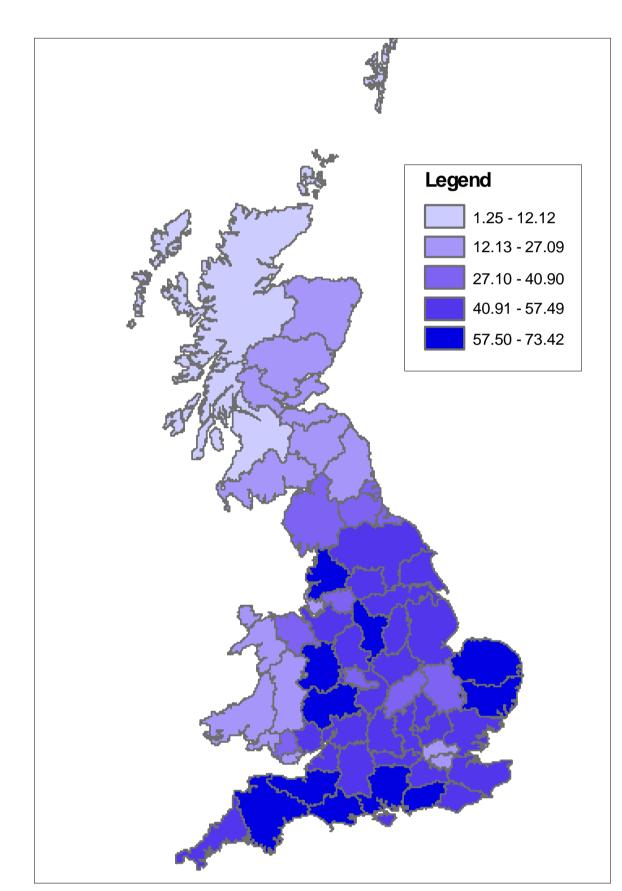
An extract of the Great Britain Poultry Register (GBPR) dataset (Defra, 2009) was used to obtain the geographical location and size of every registered poultry farm within GB (n=23,482 farms; with a potential maximum of 6% being duplicate farms following data cleaning). The **objectives** using ArcGIS software were:

- (i) To investigate density-dependent transmission: using a count of farms located within each possible PZ and SZ, which act as a proxy for the distance over which density-dependency may operate.
- (ii) To investigate frequency-dependent transmission: using the average number of daily catching company (cc) team visits per farm, estimated from Dent et al. (2009), with visit frequency increasing with farm size.
- (iii) To calculate a comparative ratio: by dividing the density-dependent value by the frequency-dependent value for each farm, to demonstrate variation in model dependency.

Each of the three analyses above were then averaged on a county level to explore regional differences across GB.



County average Figure poultry farm count within 3km zones (range: 1 - 8.5 farms).



County Figure average poultry farm count within 10km zones (range: 1.3 - 73.4 farms).

(i) Density-dependent transmission

The number of farms captured within the PZ's (Figures 1 and 3) and SZ's (Figures 2 and 4) varied across GB; with more farms per zone in England than Scotland, reflecting the difference in premise density.

(ii) Frequency-dependent transmission

Average (median) number of daily cc visits, approximated from Dent et al., 2009:

- <100k birds = 0.053 per day
- 100k-200k birds = 0.107 per day
- >200k birds = 0.214 per day

The average daily cc visits were found to vary by county (Figure 5), reflecting county variation in average farm size.

(iii) Comparative ratio

Figures 6 and 7 represent normalised county averages of model dependency. **Between-county** variation and a marked difference between Scotland and England was observed.

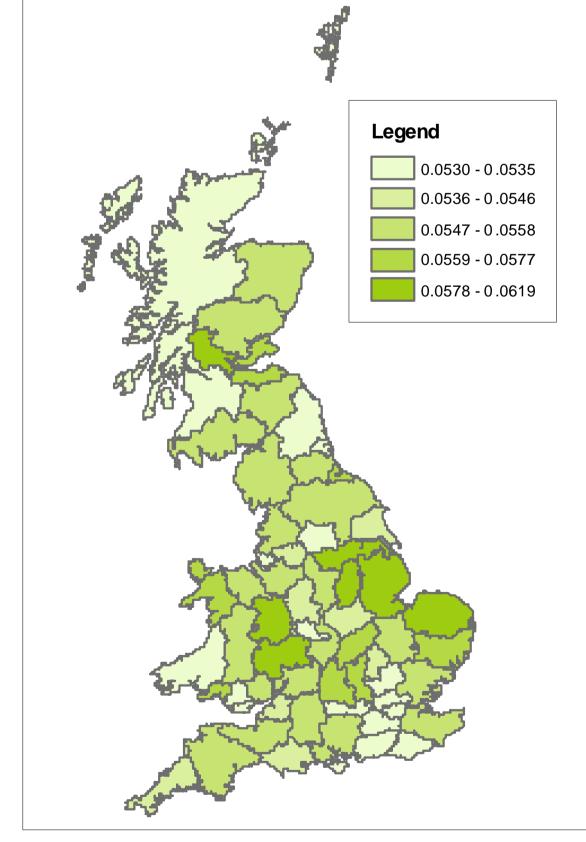


Figure 5. County average daily **CC** visit frequencies. (range: 0.053 - 0.062 visits).

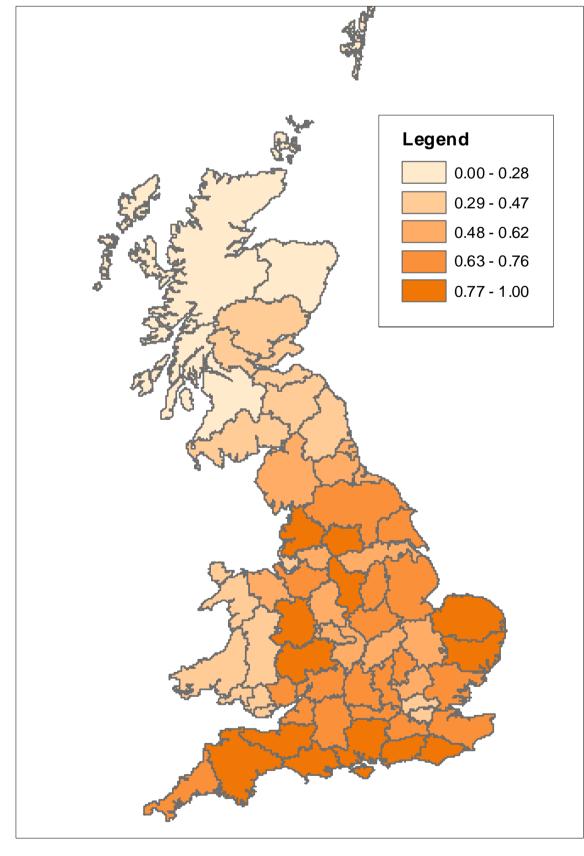


Figure 6. Farm count within 3km zones divided by CC visits, averaged by county (normalised by max county average value).

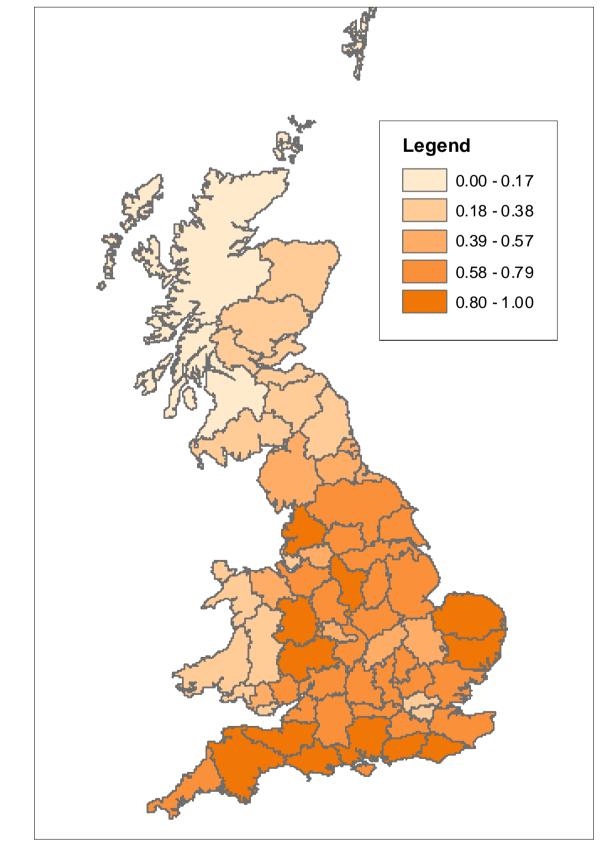


Figure 7. Farm count within **10km** zones divided by CC visits, averaged by county (normalised by max county average value).

Conclusion

The substantial regional differences in the comparative ratios suggests that both geographic location and transmission mode may affect our ability to predict the potential effectiveness of control zones. Further work in underway to quantify, on a regional level, the potential effectiveness of these control measures under different transmission assumptions using simulated models.